

# Groupe de réflexion "Automatique et IA" du GDR MACS

Christophe PRIEUR, Gipsa-lab

Congrès SAGIP et Journées Automatique  
Novembre 2020

Contacts : Isabelle QUEINNEC et Dimitri PEAUCELLE  
avec le GDR MACS

## Questions

- Qu'est ce que l'IA ?
- Quelques points importants sur l'IA et Automatique ?
- Pourquoi ces liens sont importants pour l'automatique ? Pour l'IA ?
- Quels sont les succès dans ce domaine ?
- Quelles actions pourrait-on entreprendre ?

## 3 animateurs

- Marion GILSON,
- Franck PLESTAN,
- Christophe PRIEUR.

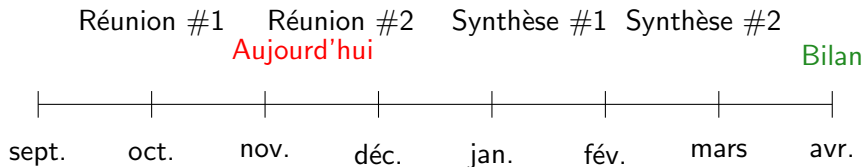
## Pour 3 groupes

- Thierry GUERRA (LAMIH), Jose-Alvaro PEREZ-GONZALEZ (Thales), Franck PLESTAN (LS2N), Romain POSTOYAN (CRAN), Sophie TARBOURIECH (LAAS),
- Sylvain DURAND (ICube), Héléne EVAÏN (CNES), Milan KORDA (LAAS), Mihaly PETRECSZKY (Cristal), Christophe PRIEUR (Gipsa),
- Vincent ANDRIEU (Lagep), Martine GANET-SCHOELLER (Groupe Ariane), Marion GILSON (CRAN), Antoine GIRARD (L2S), Guillaume MERCÉRE (LIAS).

## Fonctionnement

- 2 réunions en sous-groupe
- puis réunion plénière avec synthèses successives
- synthèse avril 2021

## Calendrier



Expérience très enrichissante.

Réunions:

- en sous-groupe non-thématique
- échanges informels, courts, *chacun présente à tout le monde*
- courte échéance

Premières réponses sur les liens IA et Automatique

## Classical issues in automatic control

- 1 identification
- 2 simulation
- 3 observation
- 4 control and performance

for dynamical systems, in presence of uncertainties, heterogeneities, constraints...

## Proposed solutions

- 1 reduced-order modeling
- 2 performance certifications
- 3 observation and control *could be done separately*
- 4 cascade, feedback and series are possible

## Classical issues in automatic control

- 1 identification
- 2 simulation
- 3 observation
- 4 control and performance

for dynamical systems, in presence of uncertainties, heterogeneities, constraints...

## Proposed solutions

- 1 reduced-order modeling
- 2 performance certifications
- 3 observation and control *could be* done separately
- 4 cascade, feedback and series are possible

## Opportunities

- 1 scientific computation
- 2 big data, sensors are everywhere
- 3 optimization and efficient algorithms
- 4 recording of long time-scale signals is possible

## Proposed solutions

- 1 large neural networks
- 2 efficient applications
- 3 automatic learning and processing

Already many successes that were not possible 3 years ago.



## Matchmaking between AI and sismology

Recent work of Michel Campillo to detect seismic signals [Seydoux et al., *Nature Com.*; 2020]:

- uses [Agen, Mallat; 2014] wavelet on  $10^{10}$  samples on a year for one station
- scattering network to compute clusters
- **Human Intelligence is needed but Artificial Intelligence helps**
- work in progress in sismology: 800 stations in Alps, on decades.

Matchmaking of Automatic Control and AI?  
In both directions?

## Matchmaking between AI and sismology

Recent work of Michel Campillo to detect seismic signals [Seydoux et al., *Nature Com.*; 2020]:

- uses [Agen, Mallat; 2014] wavelet on  $10^{10}$  samples on a year for one station
- scattering network to compute clusters
- **Human Intelligence is needed but Artificial Intelligence helps**
- work in progress in sismology: 800 stations in Alps, on decades.

Matchmaking of Automatic Control and AI?  
In both directions?

# In modelling and model reduction

For many physical problems, models are very complex, space-varying

AI techniques + Physical models allow to

- solve complex dynamical systems

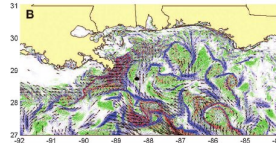
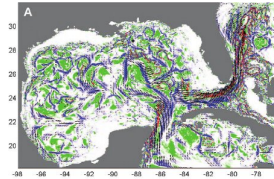
$$\begin{aligned}\dot{x} &= f(x) \\ y &= h(x)\end{aligned}$$

and to get training data

- fix the structure:

$$\begin{aligned}\dot{\hat{x}} &= A\hat{x} \\ y &= C\hat{x}\end{aligned}$$

- find the best  $A$  and  $C$ , by solving a convex problem



Gulf of Mexico  
with Kupman  
operator  
approach.

# In modelling and model reduction

For many physical problems, models are very complex, space-varying

AI techniques + Physical models allow to

- solve complex dynamical systems

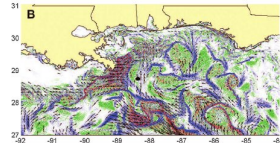
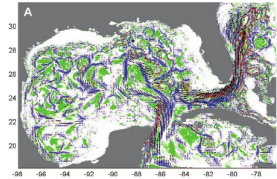
$$\begin{aligned}\dot{x} &= f(x) \\ y &= h(x)\end{aligned}$$

and to get training data

- fix the structure:

$$\begin{aligned}\dot{\hat{x}} &= A\hat{x} \\ y &= C\hat{x}\end{aligned}$$

- find the best  $A$  and  $C$ , by solving a convex problem



Gulf of Mexico  
with Kupman  
operator  
approach.

# In modelling and model reduction

For many physical problems, models are very complex, space-varying

AI techniques + Physical models allow to

- solve complex dynamical systems

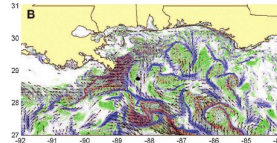
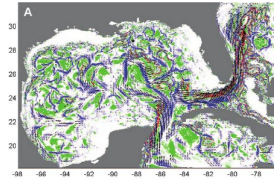
$$\begin{aligned}\dot{x} &= f(x) \\ y &= h(x)\end{aligned}$$

and to get training data

- fix the structure:

$$\begin{aligned}\dot{\hat{x}} &= A\hat{x} \\ y &= C\hat{x}\end{aligned}$$

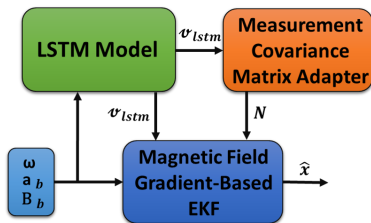
- find the best  $A$  and  $C$ , by solving a convex problem



Gulf of Mexico  
with Kupman  
operator  
approach.

# Other examples in observation and control

- Machine learning + Kalman filter for observation problem:

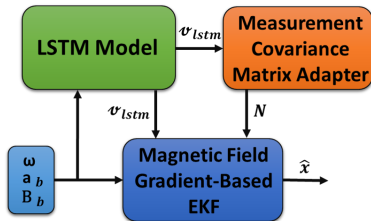


(see also some of these presentations)

- Learning + Adaptive Control for control design  
MPC+optimization  
Sensitivity analysis+control design for stability and performance  
(see Lina Guan's presentation)

# Other examples in observation and control

- Machine learning + Kalman filter for observation problem:



(see also some of these presentations)

- Learning + Adaptive Control for control design  
MPC+optimization  
Sensitivity analysis+control design for stability and performance  
(see Lina Guan's presentation)

# What can control gain from AI?

A lot:

- **Algorithmic**

Reinforcement learning / Iterative learning control / real time optimization

Automatic differentiation

Model reduction using AI

System identification or parameter calibration

Fictitious measures for observation with machine learning

Links with adaptive control

- **Practical solutions** to address control problems

- **Hardware and architectures**

Tailored hardware and software for AI (e.g., Tensor Processing Units)

Design control algorithms with such architectures in mind?



# What can control gain from AI?

A lot:

- **Algorithmic**

Reinforcement learning / Iterative learning control / real time optimization

Automatic differentiation

Model reduction using AI

System identification or parameter calibration

Fictitious measures for observation with machine learning

Links with adaptive control

- **Practical solutions** to address control problems

- **Hardware and architectures**

Tailored hardware and software for AI (e.g., Tensor Processing Units)

Design control algorithms with such architectures in mind?

# What can control gain from AI?

A lot:

- **Algorithmic**

Reinforcement learning / Iterative learning control / real time optimization

Automatic differentiation

Model reduction using AI

System identification or parameter calibration

Fictitious measures for observation with machine learning

Links with adaptive control

- **Practical solutions** to address control problems

- **Hardware and architectures**

Tailored hardware and software for AI (e.g., Tensor Processing Units)

Design control algorithms with such architectures in mind?

# What can control give to AI?

A lot, as well! (But maybe still to be better explained?)

- Some AI problems are control problems  
e.g., robot walking, or human-robot collaborative tasks, or robots catching flying objects
- Some AI problems have an intrinsic dynamical component  
e.g., video processing (Kalman filter, consensus approach)  
System theory for recurrent neural networks, reservoir computing  
Control theory to recurrent neural networks  
Why persistence of excitations in AI could help?
- Some AI tools need verification (safety, stability)  
e.g., Lyapunov techniques, barrier certificates, proofs of AI algorithms.

# What can control give to AI?

A lot, as well! (But maybe still to be better explained?)

- Some AI problems are control problems  
e.g., robot walking, or human-robot collaborative tasks, or robots catching flying objects
- Some AI problems have an intrinsic dynamical component  
e.g., video processing (Kalman filter, consensus approach)  
System theory for recurrent neural networks, reservoir computing  
Control theory to recurrent neural networks  
Why persistence of excitations in AI could help?
- Some AI tools need verification (safety, stability)  
e.g., Lyapunov techniques, barrier certificates, proofs of AI algorithms.

# What can control give to AI?

A lot, as well! (But maybe still to be better explained?)

- **Some AI problems are control problems**  
e.g., robot walking, or human-robot collaborative tasks, or robots catching flying objects
- Some AI problems have an **intrinsic dynamical component**  
e.g., video processing (Kalman filter, consensus approach)  
System theory for recurrent neural networks, reservoir computing  
Control theory to recurrent neural networks  
Why persistence of excitations in AI could help?
- Some AI tools need **verification** (safety, stability)  
e.g., Lyapunov techniques, barrier certificates, proofs of AI algorithms.

# Conclusion so far on Automatic Control and AI

Already many and various successes in the French community. ✓  
Not so many multidisciplinary research. ✗

Many opportunities ✓  
but only a few participations to the French community to

- industrial transfer ✗
- international projects ✗
- international conferences ✗

Berkeley 2nd L4DC Conference

Home

Call for Papers

Accepted Papers

Invited Speakers

Agenda

Org



LEARNING FOR DYNAMICS & CONTROL (L4DC)

Online June 11-12th, 2020

We're excited to announce that the 3rd L4DC in 2021 will be happening at ETH in Zürich, Switzerland.

Further information can be found on the website: <https://l4dc.ethz.ch>



- Elaborated picture of links between AI and Control
- Actions to be done are under progress
- All comments are welcome to the working group
- Stay tuned until April!



- Elaborated picture of links between AI and Control
- Actions to be done are under progress
- All comments are welcome to the working group
- Stay tuned until April!

- Elaborated picture of links between AI and Control
- Actions to be done are under progress
- All comments are welcome to the working group
- Stay tuned until April!