

Comparative assessment of inverter control strategies in a community AC microgrid context

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DESCRIPTION AND OBJECTIVES:

In a landscape dominated by conventional power grids employing synchronous generators in charge with ensuring the grid secure operation by providing ancillary services such as voltage and frequency regulation, the inverter-based microgrids are increasingly necessary to accommodate the distributed energy resources (DERs). Most of DERs are equipped with *grid-following* inverters (GFLIs). Unlike the synchronous generators, GFLIs are not intrinsically characterized by inertial responses, therefore this transition raises technical challenges for the grid's stability. A possible solution is adoption of *grid-forming* inverters (GFMI) which can emulate the characteristics of synchronous generators if appropriately equipped with improved damping and virtual inertia [1]. Moreover, use of GFMI combined with intelligent load shedding can *enhance grid reliability and resilience* by enabling the provision of energy to critical facilities during power outages [2].

This internship is focused on providing pertinent control solutions in the larger context of community microgrids. A *community microgrid* includes several GFMI and is designed to serve the energy needs of a residential neighbourhood, a building complex, *etc.*, in both *grid-connected* and *standalone* operating modes. Community microgrids can be owned and operated by local communities in a decentralized manner, rather than by a centralized utility. A community microgrid may be defined as a *cluster of neighbouring microgrids* connected via interlinking converters, improving the reliability and economic performance of individual microgrids [3]. In this context, an individual microgrid might cooperate with neighbouring microgrids for back-up operations in emergencies and for economic purposes.

Starting from studying the dynamic behaviour and control of a single GFMI, then continuing with a simple, yet representative microgrid topology – at least two GFMI in interaction – the decentralized control of GFMI equipped with improved damping and virtual inertia is aimed at. Based on devising suitable control-oriented mathematical models, a first step will be to identify which control strategies for GFMI within a community microgrid are most effective in *grid-connected*, as well as in *standalone* modes. Ensuring a *smooth switching* between the two modes is also required. In a second step, closed-loop preliminary validations by numerical simulation will provide a basis towards experimental validation of a community microgrid on a laboratory scale.

Our study will in a first time concern the *dynamic behaviour analysis and control of a single GFMI* connected to a distribution grid. A comprehensive review, classification and critical comparison of several control strategies for GFMI in a simulation case study can be found in [4], where four major categories of GFMI have been identified: a) droop control; b) virtual synchronous machine; c) matching approach; and 4) virtual oscillator-based control. The key challenges were summarized to be further investigated prior to large-scale integration of GFMI into low-inertia grid infrastructure.

Taking into account operation of a single GFMI in a community microgrid context, control strategies must already envisage embedding a maximum of its microgrid operation constraints, that is, a decentralized control vision should be adopted from the very beginning. Use of *droop control* in both *grid-connected* and *standalone* operating modes can reasonably be taken as a baseline; other strategies should be further assessed against this latter. Not at least, the *fault ride-through* requirements of a community microgrid, considering load imbalances and short circuits, should also be taken into account in the control design. In order to satisfy the requirements set by relevant *grid codes* (e.g., SR 734.27 in Switzerland [5]), *robustness* and *optimality* of the proposed control strategy must be addressed. With this respect, the formalism of *\mathcal{H}_∞ -based robust control* design can provide a pertinent framework leading to very well-performing closed-loop behaviour [6]–[8].

MASTER THESIS OBJECTIVES:

- bibliographical search focused on identifying the most pertinent state-of-the-art control-oriented modelling and control methods of inverters in a community microgrid context
- PLECS – MATLAB®/Simulink® simulation of models and control strategies of a single inverter in both grid-following (grid-connected) and grid-forming (standalone) microgrid cases, yielding a critical assessment of performances in terms of advantages and drawbacks of each control strategy
- simulation analysis of smooth switching between the two connection cases
- study of implementation constraints on hardware microgrid topologies available at the Institut des Energies at Yverdon-les-Bains in Switzerland
- concluding on which control approaches are most effective in *grid-connected* and *standalone* operational modes with a community microgrid context

SUPERVISING:

This internship will be jointly supervised by Dr. Antoneta Iuliana BRATCU, Associate Professor HDR with Grenoble Image Parole Signal Automatique (GIPSA-lab) at University Grenoble Alpes and Grenoble Institute of Technology and Management, and Professor Mauro CARPITA and Associate Professor Mokhtar BOZORG, both with University of Applied Sciences Western Switzerland (HES-SO) and Institute of Energies, Yverdon-les-Bains, Switzerland, as a part of a collaboration between the two research units, in France and Switzerland, respectively.

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INTERNSHIP ORGANIZATION:

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